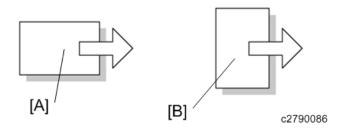
Internal Finisher SR3130 Machine Code: D690 Field Service Manual

Symbols, Abbreviations and Trademarks

Symbols, Abbreviations

This manual uses several symbols and abbreviations. The meaning of those symbols and abbreviations are as follows:

Symbol	What it means
W	Clip ring
©P	Screw
F	Connector
Ş	Clamp
B	E-ring
\$ \$\$	Flat Flexible Cable
0	Timing Belt
SEF	Short Edge Feed [A]
LEF	Long Edge Feed [B]
K	Black
С	Cyan
М	Magenta
Υ	Yellow
B/W, BW	Black and White
FC	Full color



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Microsoft® Windows Server® 2012 Standard

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1. Replacement and Adjustment

Main Unit

Internal Finisher

- 1. Disconnect the interface cable connected to the main machine.
- 2. Open the front cover [A]



d1462870

3. Left upper cover [A] (*\mathbb{O} \times 1)



d197f0109

4. Left rear cover [A] (🎞×2, hook×1)



d197f0043

5. Internal finisher [A] (@x1)



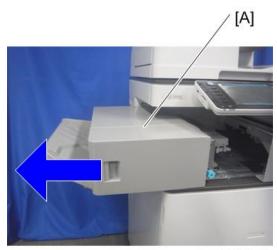
6. Bridge guide plate [A] (\$\mathfrak{O}^{\mathfrak{P}} \times 2)



Exterior Covers and Trays

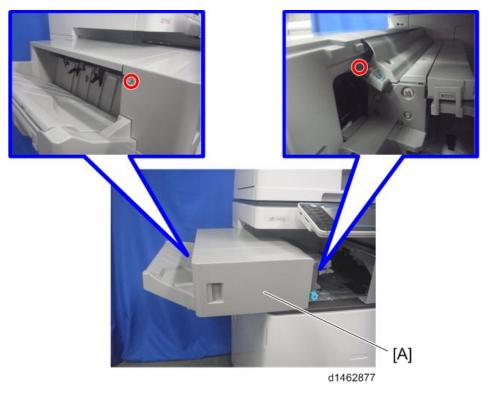
Finisher Front Cover

1. Pull the finisher [A]



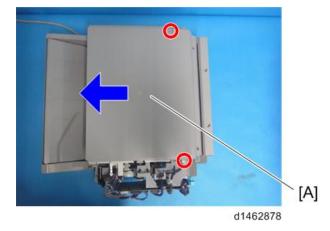
d1462876

2. Finisher front cover [A] (\$\mathbb{O}^* \times 2)



Finisher Upper Cover

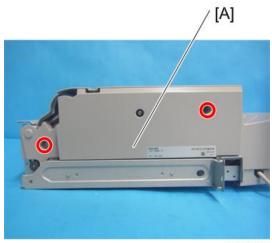
- 1. Finisher front cover (page 9)
- 2. Finisher upper cover [A] (\$\mathbb{O}^2 \times 2)



1

Finisher Rear Cover

- 1. Internal finisher (page 7)
- 2. Finisher rear cover [A] (\$\mathscr{O}^2 \times 2)\$



d1462887

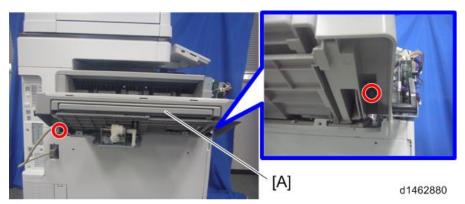
Paper Exit Tray

1. Left lower cover [A] (©×2)



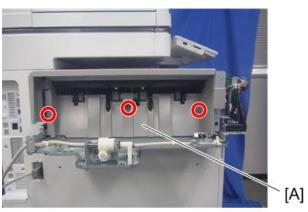
11

2. Paper exit tray [A] (@x2).



Paper Exit Cover

- 1. Paper exit tray (page 11)
- 2. Paper exit cover [A] (௴×3, ❤×3, ∜×2).



d1462881

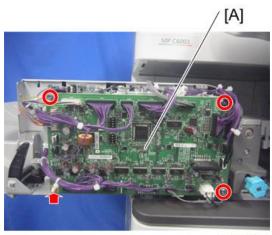
F

Board

Controller Board

ACAUTION

- When a controller board is replaced, use the same DIP switch settings as those of the controller board before replacement.
- 1. Finisher front cover (page 9)
- 2. Controller board [A] (@x3, Fxall, plastic rivetx1)



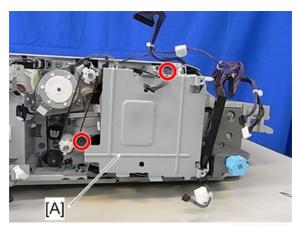
d146z0040

3. Release four clamps and remove the harness bracket [A] on the controller board bracket. (\$\infty 4\$)



d690z2001

4. Controller board bracket [A] (@x2)



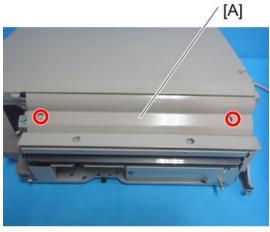
d690z2002

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Sensors

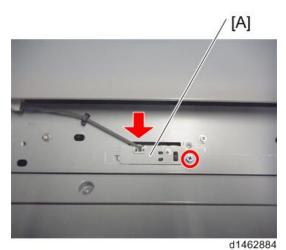
Entrance Sensor

- 1. Internal finisher (page 7)
- 2. Open/Close upper cover [A] (\$\mathbb{O}^{\times} \times 2)

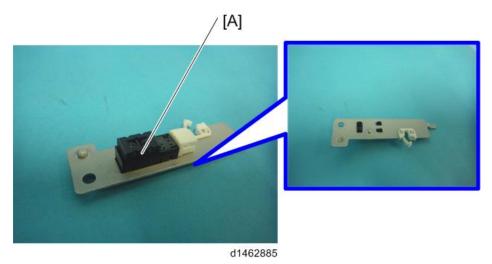


d1462883

3. Entrance sensor unit [A] (@x1, Fx1, \$x1)

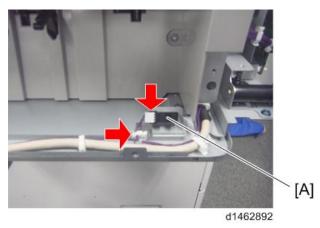


4. Entrance sensor [A]



Paper Exit Full Sensor

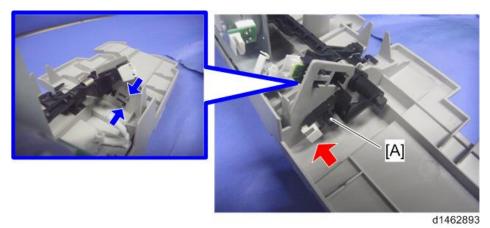
- 1. Paper exit tray (page 11)
- 2. Paper exit full sensor [A] (🍑×1, 🖘1)



Stack Height Lever HP Sensor

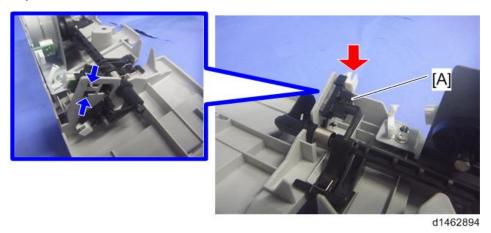
1. Paper exit cover (page 12)

2. Stack Height Lever HP Sensor [A] (**x1)



Paper Surface Sensor

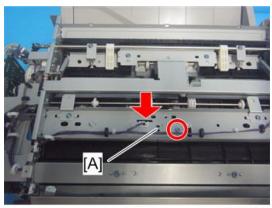
- 1. Paper exit cover (page 12)
- 2. Paper surface sensor [A] (**x1)



Transport Sensor

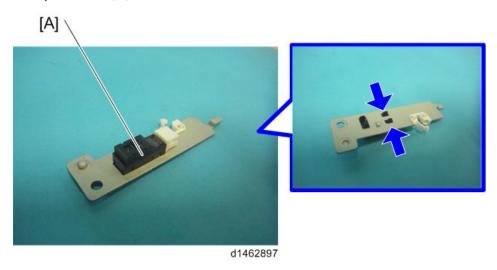
1. Finisher upper cover (page 10)

2. Transport sensor unit [A] (🏵×1, 🍑×1, 🖘1)



d1462896

3. Transport sensor [A]

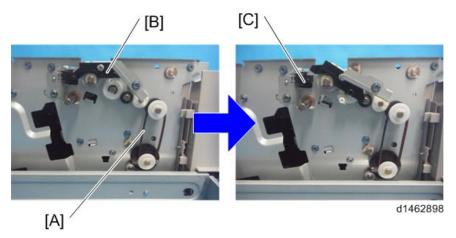


Positioning Roller Home Position Sensor

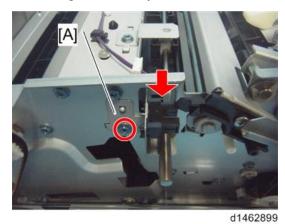
- 1. Finisher upper cover (page 10)
- 2. Finisher rear cover (page 11)

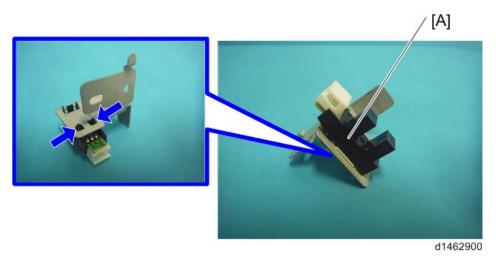
п

3. Rotate the timing belt [A], and release the positioning roller arm unit [B] from the positioning roller HP sensor [C].



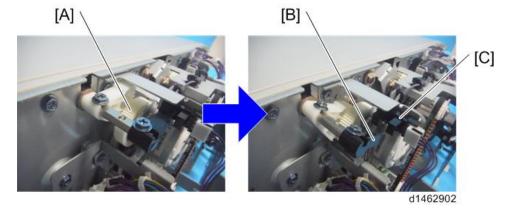
4. Positioning roller home position sensor unit [A] (@*x1, @*x1, @*x1)



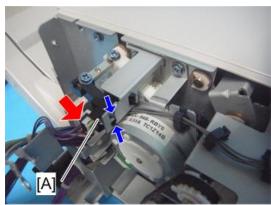


Paper Exit Guide Plate Home Position Sensor

- 1. Controller board (page 13)
- 2. Rotate the paper exit guide plate gear [A] counterclockwise, and release the paper exit guide plate [B] from the paper exit guide plate HP sensor [C].



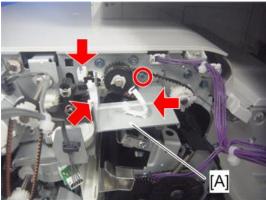
3. Paper Exit Guide Plate Home Position Sensor [A] (**x1)



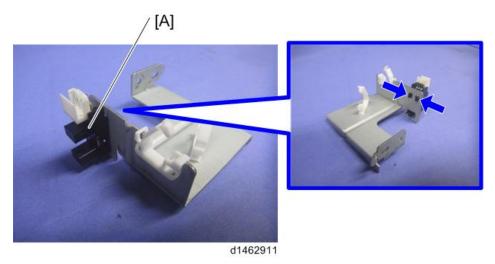
d1462903

Shift Roller Home Position Sensor

- 1. Controller board bracket (page 13)
- 2. Shift roller home position sensor unit [A] (♂×1, ♂×1, ∜×2)

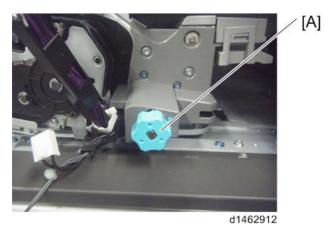


d1462910

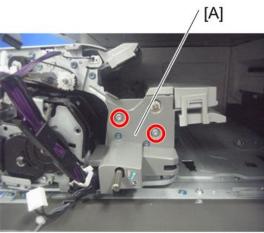


Stapler Home Position Sensor

- 1. Controller board bracket (page 13)
- 2. Knob [A]

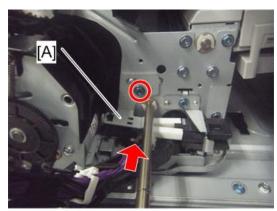


3. Entrance cover [A] (©°×2)



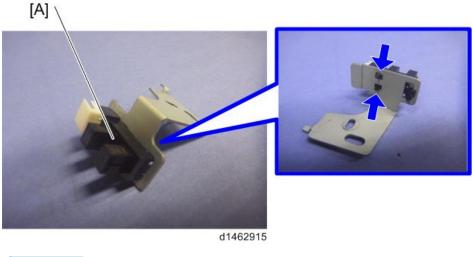
d1462913

4. Stapler home position sensor unit [A] (@x1, @x1)



d1462914

5. Stapler home position sensor [A]

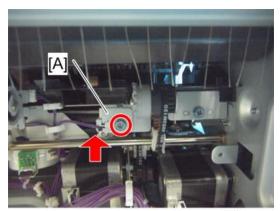


UNote

• If it is difficult to remove or attach the sensor, push the stapler unit inside.

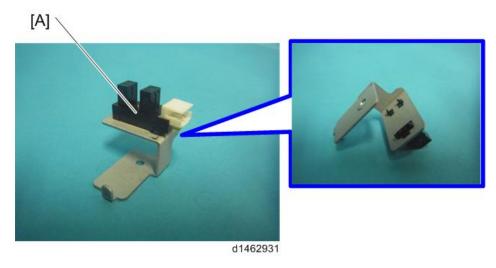
Jogger Fence Home Position Sensor (Front)

- 1. Paper exit cover (page 12)
- 2. Jogger fence home position sensor (front) unit [A] (\$\mathcal{O}^* \times 1, \$\mathcal{O}^* \times 1, \$\mathcal{O}^* \times 1\$)



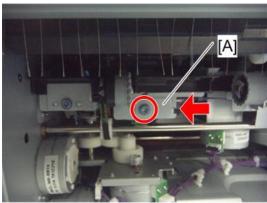
d1462932

3. Jogger fence home position sensor (front) [A]



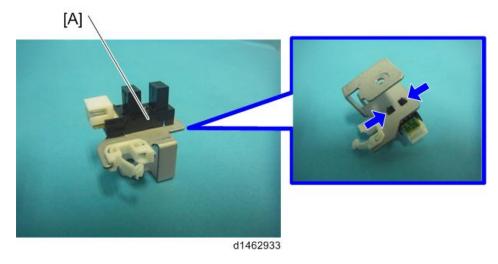
Jogger Fence Home Position Sensor (Rear)

- 1. Paper exit cover (page 12)
- 2. Jogger fence home position sensor (rear) unit [A] (0"×1, 0"×1)



d1462930

3. Jogger fence home position sensor (rear) [A]



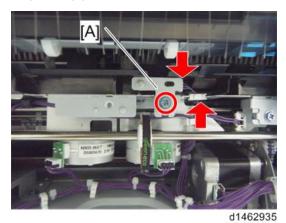
Stapler Tray Jam Sensor

- 1. Paper exit cover (page 12)
- 2. Paper exit roller unit [A] (@x1)



П

3. Stapler tray jam sensor unit [A] (ॐ×1, ॐ×1, ॐ×1)



4. Stapler tray jam sensor [A] (🖤×1)

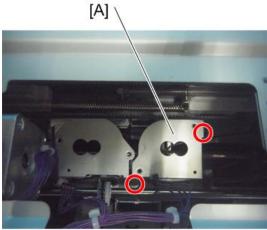


d1462936

Paper Sensor

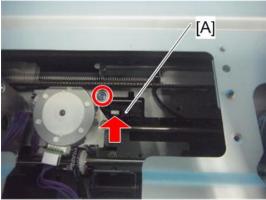
1. Jogger fence motor (rear) (page 37)

2. Jogger fence motor (rear) bracket [A] (ॐ×2, ॐ×3)



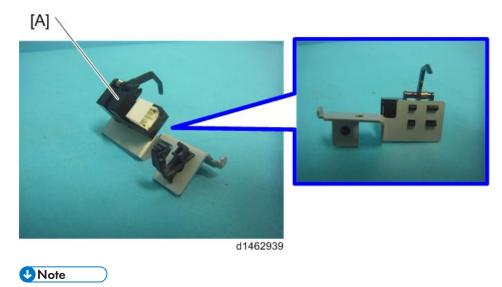
d1462937

3. Paper sensor unit [A] (@x1, Fx1, \$x1)



d1462938

4. Paper sensor [A]



• When installing this sensor, be careful not to damage the sensor actuator.

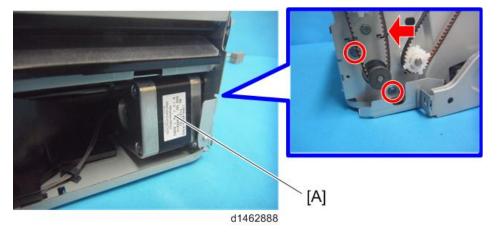
Motors

Entrance Motor

- 1. Finisher rear cover (page 11)
- 2. Finisher right rear bracket [A] (**2)



3. Entrance motor [A] (\$\mathfrak{O}^{\mathfrak{o}} \times 2, \$\mathfrak{O}^{\mathfrak{o}} \times 1, Timing belt*1)



Tray Lift Motor

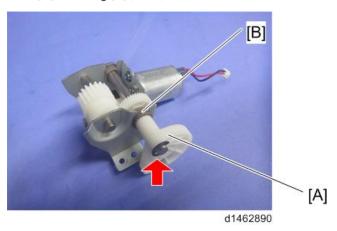
1. Paper exit tray (page 11)

1

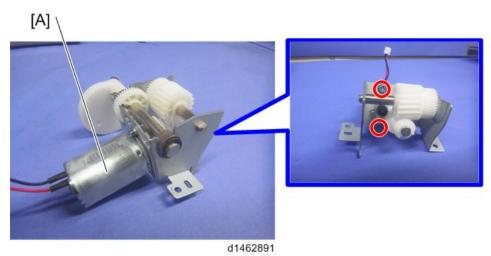
2. Tray lift motor unit [A] (⊕×2, ⊕×1, ≪×1)



3. Cam [A], bearing [B] (🔊×1)

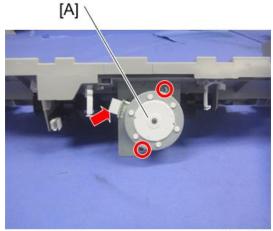


4. Tray lift motor [A] (9 ×2)



Stack Height Lever Motor

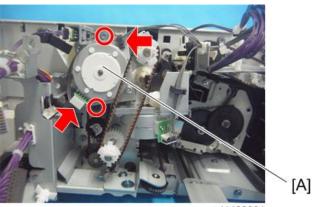
- 1. Paper exit cover (page 12)
- 2. Stack height lever motor [A] (@x2, &x1)



d146z0041

Paper Exit Guide Plate Motor

- 1. Controller board (page 13)
- 2. Paper exit guide plate motor [A] (\$\mathbb{O}^* \times 2, \$\mathbb{O}^* \times 1, \$\mathbb{N} \times 1\$)



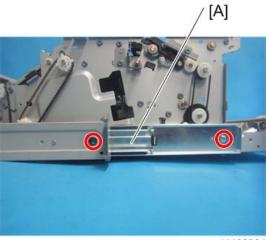
d1462901

Positioning Roller Motor

1. Paper exit cover (page 12)

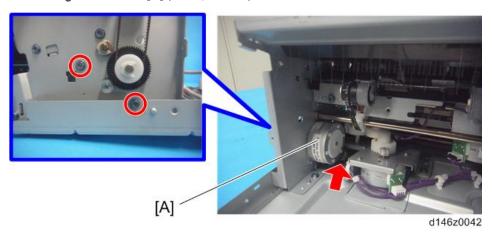
П

- 2. Finisher rear cover (page 11)
- 3. Rear rail [A] (\$\mathbb{O}^{\mathbb{N}} \times 2)



d1462904

4. Positioning roller motor [A] (\$\mathbb{O}^* \times 2, \$\mathbb{O}^* \times 1)\$

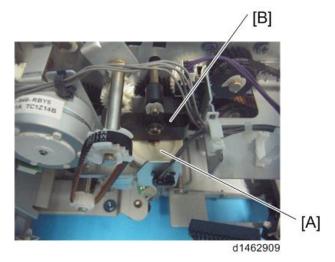


Shift Motor

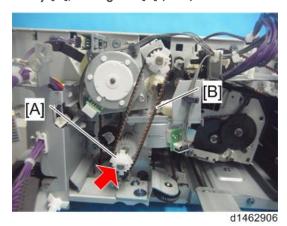
ACAUTION

- After attaching, rotate the knob, and check that all gear trains can rotate.
- After attachment, when the cam [A] is rotated, check that the link [B] interlocks.

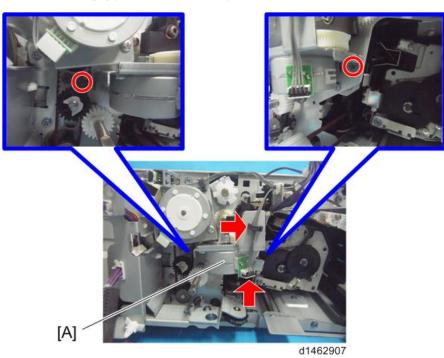




- 1. Controller board bracket (page 13)
- 2. Pulley [A], Timing belt [B] (\$\mathbb{B} \times 1)



3. Shift motor unit [A] (⊕×2, ⊕×1, ⊕×1)



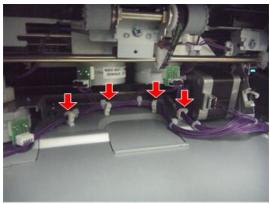
4. Shift motor [A] (\$\mathbb{O}^* \times 2).



Stapler Retreat Motor

ACAUTION

- When placing the finisher upside down, be careful not to deform the frame.
- 1. Paper exit cover (page 12)

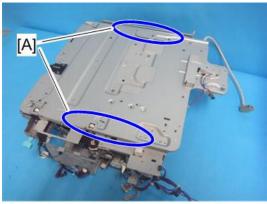


d1462916

Place the internal finisher upside down on the table while holding the parts shown below [A].



• Hold the parts [A] shown below to lift the internal finisher. Otherwise, other brackets and parts may be deformed.



d1462917

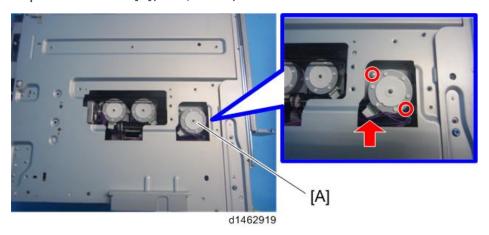
1

1

4. Base cover [A] (🖤×3)

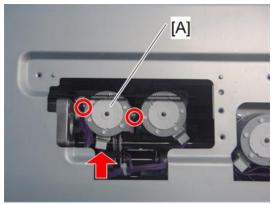


5. Stapler retreat motor [A](@×2, &*×1)



Jogger Fence Motor (Front / Rear)

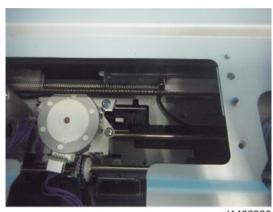
1. Base cover (page 35)



d1462927

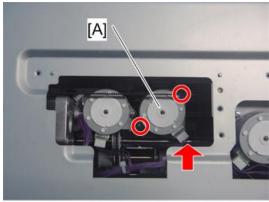
UNote

• During re-assembly, remove the jogger fence motor (rear) bracket, and check that the motor pulley has not separated from the timing belt.



d1462928

3. Jogger fence motor (rear) [A] (@x2, Fx1, Timing beltx1)



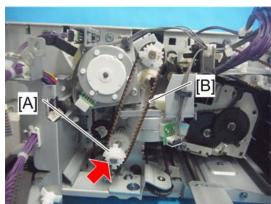
d1462929

U Note

• During re-assembly, check that the motor pulley has not separated from the timing belt.

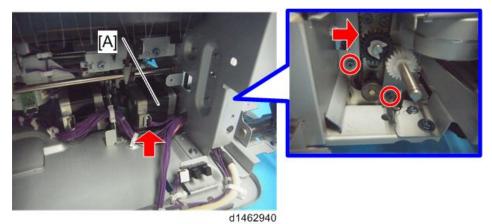
Transport Motor

- 1. Paper exit cover (page 12)
- 2. Controller board (page 13)
- 3. Finisher rear cover (page 11)
- 4. Pulley [A], Timing belt [B] (\$\mathbb{B} \times 1).



d1462906

5. Transport Motor [A] (\$\text{\$\text{\$\infty}\$} \times 2, \$\times \times 1, \text{ Timing belt} \times 1)



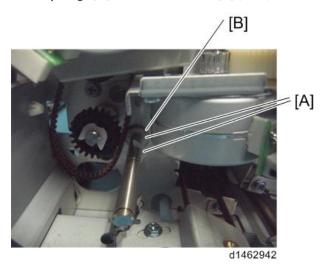
Paper Exit Motor

- 1. Transport motor (page 39)
- 2. Controller board bracket (page 13)
- 3. Gear [A] (🕅×1)

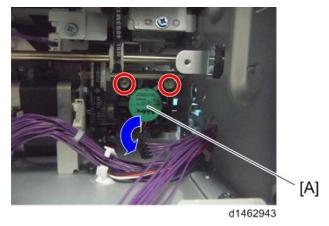


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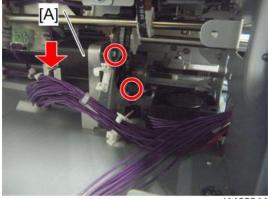
4. Two clip rings [A] and Shaft bracket [B] (\$\mathbb{B}\timex2).



5. Remove the screws of the fan [A] and then lay it down (\Im ×2).



6. Paper Exit Motor [A] (@x2, Fx1).



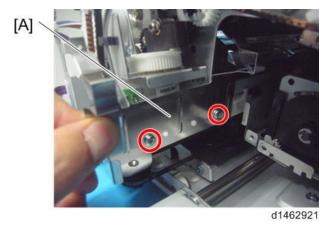
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Stapler Unit

- 1. Controller board bracket (page 13)
- 2. Insert the stapler unit [A] into the rear.



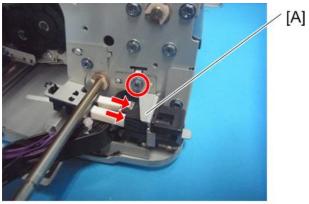
3. Rear trailing edge fence [A] (\$\mathbb{O}^{\times} \times 2)\$



4. Stapler home position sensor (page 22)

1

5. Cover open/close switch unit [A] (@×1, @×2)

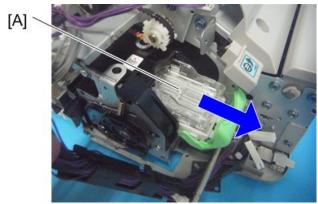


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6. Harness guide unit [A] (@x1)



7. Move the stapler unit to the front, and remove the cartridge [A].



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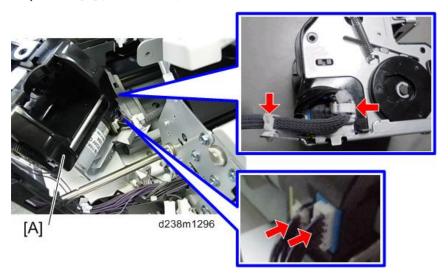
U Note

- During re-assembly, install the cartridge last.
- 8. Remove the unit fixing screw of the stapler unit. ($\mathfrak{S}^* \times 1$)



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9. Stapler unit [A] ([®]×2, [™]×2)

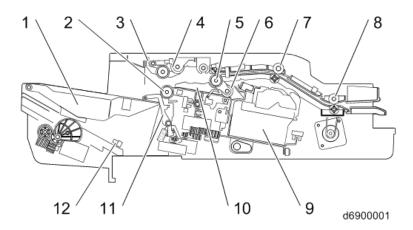


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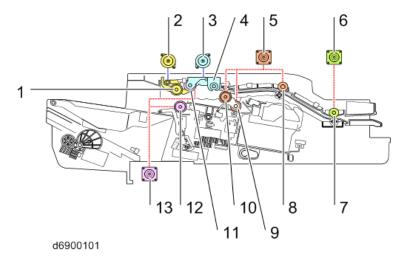
2. Detailed Descriptions

Internal Finisher SR3130 (D690)

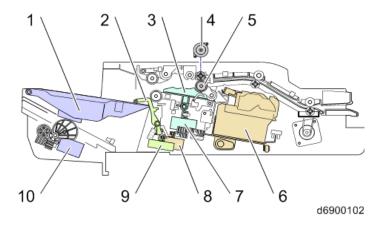
Parts Layout



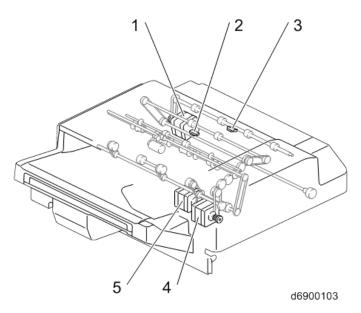
No.	Description	No.	Description
1	Paper exit tray	7	Transport roller
2	Paper ejection roller	8	Entrance roller
3	Paper exit open/close guide plate	9	Stapler
4	Positioning roller	10	Staple tray (jogger)
5	Shift roller	11	Stack height detection lever
6	Reverse roller	12	Full sensor



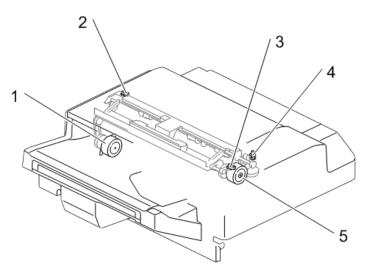
No.	Description	No.	Description
1	Paper exit open/close guide plate	8	Transport roller
2	Paper exit open/close guide plate motor	9	Reverse roller
3	Positioning roller motor	10	Shift roller
4	Positioning roller unit	11	Positioning roller
5	Transport motor	12	Paper ejection roller
6	Entrance motor	13	Paper exit motor
7	Entrance roller		



No.	Description	No.	Description
1	Paper exit tray	6	Stapler
2	Stack height detection lever	7	Jogger motor
3	Staple tray (jogger)	8	Stapler retreat motor
4	Shift motor	9	Stack height lever motor
5	Shift roller	10	Tray lift motor

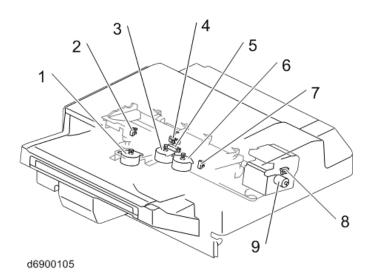


No.	Description	No.	Description
1	Entrance motor	4	Transport motor
2	Transport sensor	5	Paper exit motor
3	Entrance sensor		



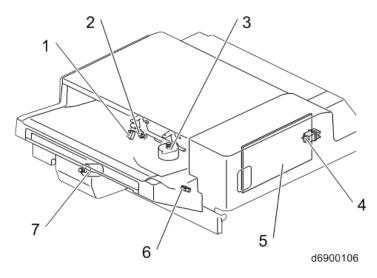
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No.	Description	No.	Description
1	Positioning roller motor	4	Shift roller Home Position sensor
2	Positioning roller Home Position sensor	5	Paper exit guide plate motor
3	Paper exit guide plate Home Position sensor		



No.	Description	No.	Description
1	Stapler retreat motor	6	Jogger fence motor (front)

No.	Description	No.	Description
2	Jogger fence Home Position sensor (rear)	7	Jogger fence Home Position sensor (front)
3	Jogger fence motor (rear)	8	Stapler Home Position sensor
4	Paper sensor	9	Stapler motor
5	Stapler tray jam sensor		



No.	Description	No.	Description
1	Stack height lever HP sensor	5	Controller board
2	Paper surface sensor	6	Full sensor
3	Stack height lever motor	7	Tray lift motor
4	Cover open/close switch		

Mechanism

Straight paper ejection mechanism

Paper ejected from the printer unit is transported by a transport roller and eject roller via an entrance roller. These are driven by entrance motor, transport motor and eject motor which permit linear speed correspondence. The paper exit driven roller stands by at a certain distance from the paper exit roller,

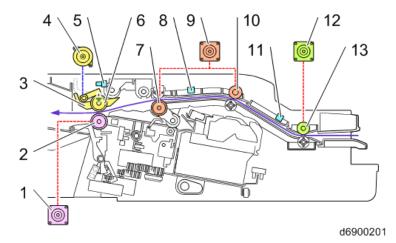
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and its descent/ascent is performed by an eject guide plate movable motor depending on the detection timing of the sensors (motor operates CW/CCW).

The paper eject open/close guide plate descent/ascent timings are as follows:

- Descent: Paper rear edge passes entrance sensor
- Ascent: Paper rear edge passes transport sensor

The eject guide plate is provided with a Home Position sensor which detects the home position during ascent.



No.	Description	No.	Description
1	Paper exit motor	8	Transport sensor
2	Paper exit roller	9	Transport motor
3	Paper exit open/close guide plate	10	Transport roller
4	Paper exit guide plate motor	11	Entrance sensor
5	Paper exit open/close guide plate Home Position sensor	12	Entrance motor
6	Paper exit driven roller	13	Entrance roller
7	Shift roller		

Shift eject mechanism

As with straight eject, shift eject is also done by transporting the paper to a transport roller and an eject roller via an entrance roller.

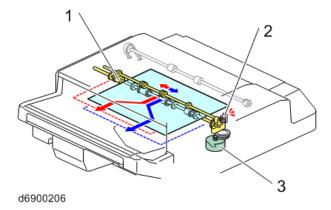
In shift operation, a shift roller is moved from front to back during transport by the driver of a shift motor.

Shift roller operation timings are as follows:

- Shift operation: Paper rear edge passes entrance sensor
- Return to original position: Paper rear edge passes transport sensor

The shift roller detects the home position by a Home Position sensor.

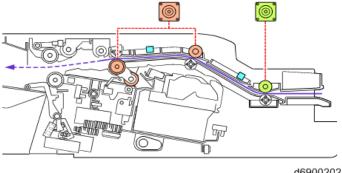
The shift roller motor operates CW/CCW, and shifts the paper from front to back. The home position is located at the back of the displacement range, and is detected by a Home Position sensor.



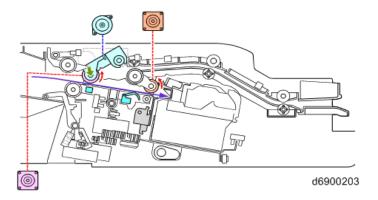
No.	Description	No.	Description
1	Shift roller	3	Shift motor
2	Shift roller Home Position sensor		

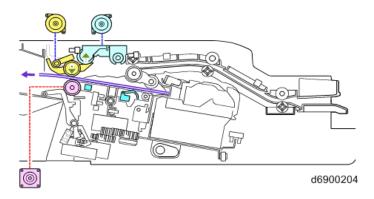
Staple eject mechanism

Staple eject requires that transported paper is temporarily stored in a staple tray. After rear edge detection of the transported paper is performed by a transport sensor, a positioning roller unit descends and transports it to a staple tray.



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Positioning roller ascent/descent mechanism

The positioning roller unit is made to ascend/descend by a positioning roller up/down drive motor (the motor operates CW/CCW), and its position is detected by a Home Position sensor. The positioning roller rotates in the opposite direction to the transport roller, and has the function of transporting paper to the back of the staple tray.

Paper rear edge alignment mechanism

The rear edge of paper transported by the positioning roller is made to project against a rear trailing edge fence by a reverse roller. It rotates continuously until the bundle of paper is ejected after it is stapled.

The reverse roller is driven from a transport roller via a gear, and is always situated above the stapler tray. A driven roller is installed on the side of the stapler tray which reduces wear of the reverse roller.

Paper detection on stapler tray

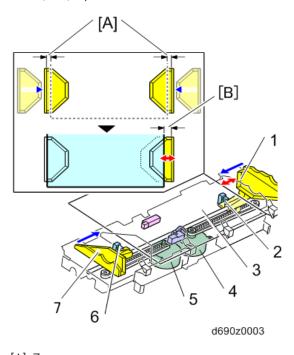
The stapler tray is provided with the following sensors which detect paper status in the tray.

- Paper jam in tray: tray jam sensor
- Paper present/absent in tray: paper sensor

Jogger mechanism (paper alignment)

Paper transported to the stapler tray is aligned one sheet at a time by a jogger fence. The jogger fences are driven forwards and backwards independently, and align the paper with the tray center. Jogger fence drives are installed at the front and back. Home Position sensors are also installed at the front and back.

When the paper alignment is performed, the jogger fences move from the home position, and stand by 7 mm away from the paper to be stapled. When the paper is then transported to the tray, the jogger fence (rear) moves according to the paper size and aligns the paper. The jogger fence (rear) stands by 7 mm away from the paper, and again moves 7 mm towards the paper in order to perform paper alignment, so it moves a total of 14 mm. During the paper alignment, the jogger fence (rear) repeats this movement.



[A]: 7mm [B]: 14mm

No.	Description	No.	Description
1	Jogger fence (rear)	5	Jogger fence displacement motor (front)
2	Jogger fence Home Position sensor (rear)	6	Jogger fence Home Position sensor (front)
3	Stapler tray	7	Jogger fence (front)
4	Jogger fence displacement motor (rear)		

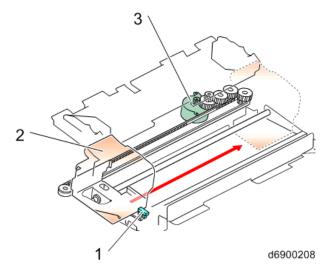
Stapler movement mechanism

Stapler specification is as follows:

- There are three stapling positions, i.e., one front parallel, one back parallel and two parallel.
- 30 large sheets or 50 small sheets can be stapled.

To change the stapling position, a mechanism is provided which moves the stapler.

The stapler is moved by a stapler motor, and the home position is detected by a Home Position sensor.



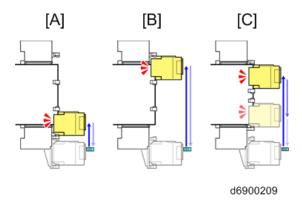
No.	Description	No.	Description
1	Stapler Home Position sensor	3	Stapler retreat motor
2	Stapler		

The stapler moves from the home position to the paper size to be stapled, and temporarily stands by. Next, the paper is transported, and after the jogger operation (paper alignment), stapling is performed.

The following picture shows the stapler standby position according to various stapling positions. From the left, there is front parallel one position, back parallel one position, and parallel two positions.

For parallel two positions, the first staple is inserted from the front, and it then moves to the back to perform stapling.

Stapling is performed back and forth, i.e., the second staple is back > front, the third staple is front > back, etc.



[A]: Front parallel, one position

[B]: Back parallel, one position

[C]: Parallel, two position

Paper eject (bundle eject)

After stapling, the eject paper open/close guide plate descends, and ejects the bundle of paper while gripping it with the eject roller.

Paper press mechanism

For ejected paper, a paper press unit is provided to immobilize the paper above the tray. It is driven by a paper press drive motor (motor operates CW/CCW)

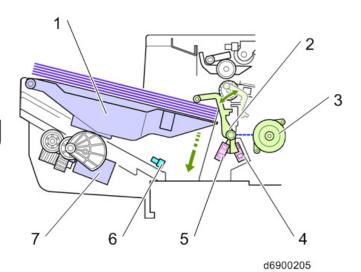
The paper press unit is provided with a paper surface sensor which detects the upper part of the paper, and a Home Position sensor which detects the home position of the paper press unit. The paper surface sensor detects the number of sheets in the tray, and if the number is large, it descends the tray to a suitable position.

Tray drive mechanism

The eject tray has a mechanism which descends the tray to a suitable position. This is driven by a tray drive motor (motor operates CW/CCW). It operates when the paper surface sensor cannot detect paper in the tray, and descends the eject tray until detection is performed.

Tray full detection mechanism

When the eject tray descends to its maximum, a full detect sensor below is covered by the eject tray filler, and it is detected that the top of the tray is full. During full tray detection, paper transport is temporarily stopped. After the paper bundle is released, the tray is raised to a suitable position, and the eject operation is repeated.



No.	Description	No.	Description
1	Paper exit tray	5	Stack height lever HP sensor
2	Stack height detection lever	6	Full sensor
3	Stack height lever motor	7	Tray lift motor
4	Paper surface sensor		